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Even **non-real-time** systems have this quality. For example, the chart in ... For instance, modern chipsets include programmable **interrupt** controllers ... When **driving** a car, we've all experienced the impact of high volume; Journal of the ACM, 1973 (Available at http://portal.acm.org/citation.cfm?id=321743). ...

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minal, Xeyes, Xclock and the top **command** are executed on ... been assigned to the Non-Trust serial **driver interrupt** num- from the runqueue and enqueues it in a priority-sorted **queue**
<http://portal.acm.org/citation.cfm?id=319195.319209> with SCHED OTHER class, which is a **non real-time** policy. ...

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Performance issues based on **real-time**, reliability, and safety will be discussed ... At one time, Wonderware advertised over 200 such **drivers**. ... operation: sample commanded setpoint, compare **commanded** to the sensor-measured ... **Non-real-time** refers to background tasks that can accept a laissez-faire **ACM**, 40, No. ...

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